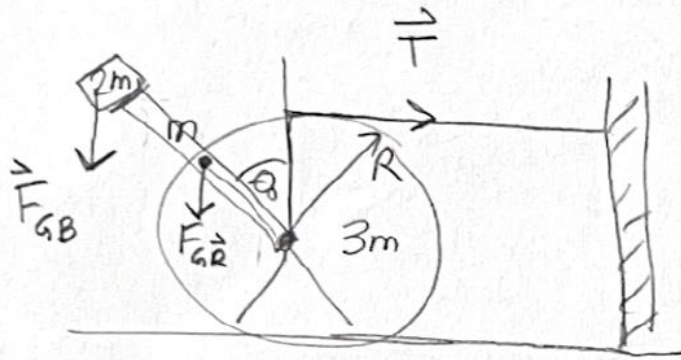


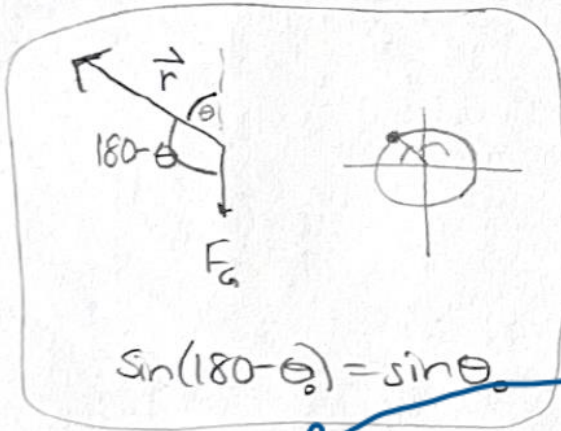
# FRQ-6 Scoring Guide

## Part a (5 points)



a)  $\sum \tau = 0$

**1 point:** For indicating that the net torque is zero, or that the clockwise and counterclockwise torques are equal



**1 point:** For a correct expression for the torque exerted by the string

**1 point:** For a correct expression for the torque exerted by the block

**1 point:** For a correct expression for the torque exerted by the rod

$$\sin(180 - \theta) = \sin \theta$$

**1 point:** For adding the counterclockwise torques and setting the sum equal to the clockwise torque (this point not awarded for just one torque)

$$-RT + F_{gB}(2R)\sin(180 - \theta) + F_{gR}(R)\sin(180 - \theta) = 0$$

$$-RT + 2mg(2R)\sin\theta + mRg\sin\theta = 0$$

$$4mgR\sin\theta + mgR\sin\theta = RT$$

$$5mg\sin\theta = T$$

- Only four points could be earned if the wrong trigonometric function was used.
- Only three points could be earned if no trigonometric function was used.

### Part b(i) (4 points)

$$I = I_{\text{disk}} + I_{\text{rod}} + I_{\text{block}}$$

$$I = \frac{3}{2}mR^2 + \frac{4}{3}mR^2 +$$

$$(2m)(2R)^2$$

$$= \frac{3}{2}mR^2 + \frac{4}{3}mR^2 + 8mR^2$$

$$= \frac{9}{6}mR^2 + \frac{8}{6}mR^2 + \frac{48}{6}mR^2$$

$$= \frac{65}{6}mR^2$$

**1 point:** For indicating that the rotational inertia is the sum of the inertias of the disk, rod, and block.

**1 point:** For calculating the total rotational inertia

**1 point:** For an answer consistent with the values use for torque and rotational inertia

b) immediately:

$$1) \quad \sum \tau = I\alpha$$

$$4mgR\sin\theta + mgR\sin\theta_0 = I\alpha$$

$$5mgR\sin\theta_0 = \left(\frac{65}{6}\right)mR^2\alpha$$

$$5\left(\frac{6}{65}\right)\frac{g\sin\theta_0}{R} = \alpha$$

$$\frac{30}{65}\frac{g\sin\theta_0}{R} = \alpha$$

$$\boxed{\frac{6}{13}\frac{g\sin\theta_0}{R} = \alpha}$$

**1 point:** For a value of torque equal to the tension in (a) times R

Part b(ii) (1 points)

bii) linear accel of the end of the rod:

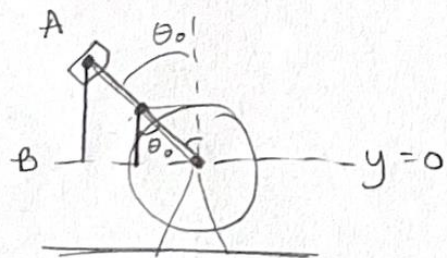
$$a_t = r\alpha, \text{ where } r = 2R$$

$$= (2R) \left( \frac{6g \sin \theta_0}{13R} \right)$$

← **1 point:** For substituting the value of  $\alpha$  and the correct radius,  $2R$ .

$$= \boxed{\frac{12}{13} g \sin \theta_0}$$

c) linear speed of the mass at the end of the rod when it is horizontal



Initial height of center of mass of rod:  $h_r = R \cos \theta_0$

Initial height of mass at end of rod:  $h_m = (2R) \cos \theta_0$

$$E_A + W_{ext} = E_B$$

$$(U_G)_{rod} + (U_G)_{mass} + 0 = \frac{1}{2} I \omega^2$$

$$mg(R \cos \theta_0) + 2mg(2R \cos \theta_0) = \frac{1}{2} \left( \frac{65}{6} m R^2 \right) \omega^2$$

$$5mgR \cos \theta_0 = \frac{65}{12} m R^2 \omega^2$$

$$\sqrt{\frac{12g \cos \theta_0}{13R}} = \omega$$

Now I need the linear (tangential) speed of the mass:

$$v_t = r \omega$$

$$= (2R) \left( \sqrt{\frac{12g \cos \theta_0}{13R}} \right)$$

$$= 4R \sqrt{\frac{3g \cos \theta_0}{13R}}$$

$$= 4 \sqrt{\frac{3gR \cos \theta_0}{13}}$$

## Part c (5 points)

**1 point:** For indicating that energy is conserved

**1 point:** For indicating the correct kinetic energy when the rod is horizontal

**1 point:** For indicating that the potential energy of two bodies (the rod and the block) changes

**1 point:** For the correct expressions for these two potential energies

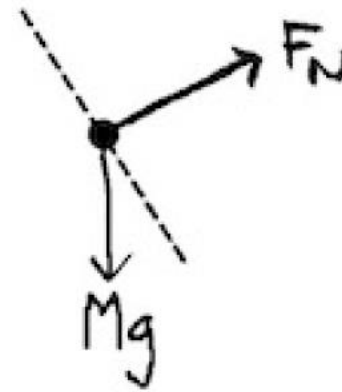
**1 point:** For using the relationship between linear and angular speed, and substituting  $\omega$  and the correct radius of  $2R$

# FRQ-7 Scoring Guide

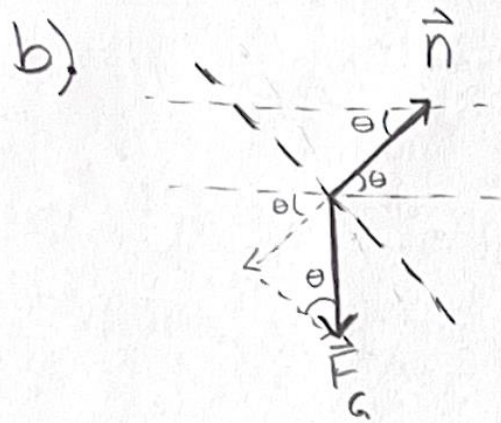
## Part a (2 points)

**1 point:** For either a weight force or a normal force, correctly drawn and labeled

**1 point:** For a second correct force and no additional forces, arrows, or components



## Part b (1 point)



$$\begin{aligned}\Sigma F_r &= n - F_{gr} \\ &= \boxed{n - F_g \sin \theta}\end{aligned}$$

**1 point:** For a correct expression for the centripetal force in terms of the forces drawn in part a.

Alternate solution  
① use energy to find  $v_c$   
 $E_A = E_c$

$$Mg(R \sin \theta + \frac{3R}{4}) = \frac{1}{2} M v_c^2$$

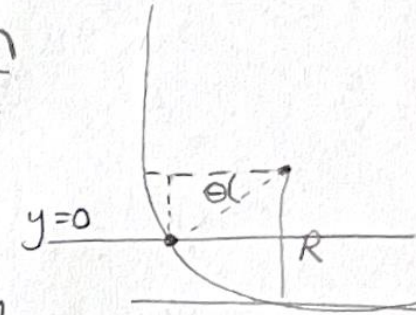
$$2g(R \sin \theta + \frac{3R}{4}) = v_c^2$$

② Then,  $\Sigma F_r = m a_r$

$$\Sigma F_r = M \left( \frac{v_c^2}{R} \right)$$

$$\Sigma F_r = \frac{M \left( 2g \left( R \sin \theta + \frac{3R}{4} \right) \right)}{R}$$

$$\Sigma F_r = \boxed{2Mg \left( \sin \theta + \frac{3}{4} \right)}$$



**OR,** for applying conservation of energy and obtaining this correct answer.

### Part c (2 points)

c) Energy principle from A to D:

$$E_A + W_{\text{ext}} = E_D$$

$$mgh_A + 0 = \frac{1}{2}mv_D^2$$

$$g\left(\frac{7R}{4}\right) = \frac{1}{2}v_D^2$$

$$\boxed{\sqrt{\frac{7gR}{2}} = v_D}$$

- $W_{\text{ext}} = 0$  if the compartment and earth are in the system.

- Initial height above D is  $R + \frac{3R}{4} = \frac{7R}{4}$

**1 point:** 1 point: For applying conservation of energy, with the loss of potential energy equal to the kinetic energy at point D

**1 point:** For a correct answer

### Part d (3 points)

d) Energy principle:

$$E_D + W_{\text{ext}} = E_E$$

$$\frac{1}{2} M v_D^2 + 0 = E_{\text{th}}$$

$$\frac{1}{2} M \left( \sqrt{\frac{7gR}{2}} \right)^2 = f_k \Delta s$$

$$\frac{1}{2} M \left( \frac{7gR}{2} \right) = \mu_k Mg (3R)$$

$$\frac{7}{4} MgR = \mu_k Mg (3R)$$

$$\frac{7}{12} = \mu_k$$

$$\boxed{.58 = \mu_k}$$

**1 point:** For equating the kinetic energy of the compartment at point D to the thermal energy at E

**1 point:** For substituting the expression for  $v_D$  from part c., and  $d = 3R$

**1 point:** For a correct expression for the frictional force

Newton's Laws + Kinematics:

$$\Sigma F_x = ma_x$$

$$-f_k n = Ma_x$$

$$-\mu_k (Mg) = Ma_x$$

$$-\mu_k g = a_x$$

$$v_{fx}^2 = v_{ix}^2 + 2a_x \Delta x$$

$$0 = \left( \sqrt{\frac{7gR}{2}} \right)^2 + 2(-\mu_k g)(3R)$$

$$0 = \frac{7gR}{2} - 6\mu_k gR$$

$$-\frac{7gR}{2} = -6\mu_k gR$$

$$\frac{7}{12} = \mu_k$$

$$\boxed{.58 = \mu_k}$$

**1 point:** For using both N2L and a kinematics equation

**1 point:** For a correct expression for the frictional force

**1 point:** For substituting the expression for  $v_D$  from part c., and  $d = 3R$

Part e(i) (2 points)

e) i) Differential equation for  $v(t)$

$$\Sigma F_x = ma_x$$

$$-kV = m \frac{dv}{dt}$$

**1 point:** For substituting the time derivative of velocity for the acceleration

**1 point:** For substituting the braking force into Newton's second law as the net force

Part e(ii) (2 points)

ii) Solve the differential equation

$$-kv = m \frac{dv}{dt}$$

$$-\frac{k}{m} dt = \frac{dv}{v}$$

$$\int -\frac{k}{m} dt = \int \frac{dv}{v}$$

$$-\frac{k}{m} t = \ln v + C$$

evaluate C.  
At  $t=0, v=V_0$

$$-\frac{k}{m}(0) = \ln V_0 + C$$

$$-\ln V_0 = C$$

write expression with  
the constant value:

$$-\frac{k}{m} t = \ln v - \ln V_0$$

$$-\frac{k}{m} t = \ln\left(\frac{v}{V_0}\right)$$

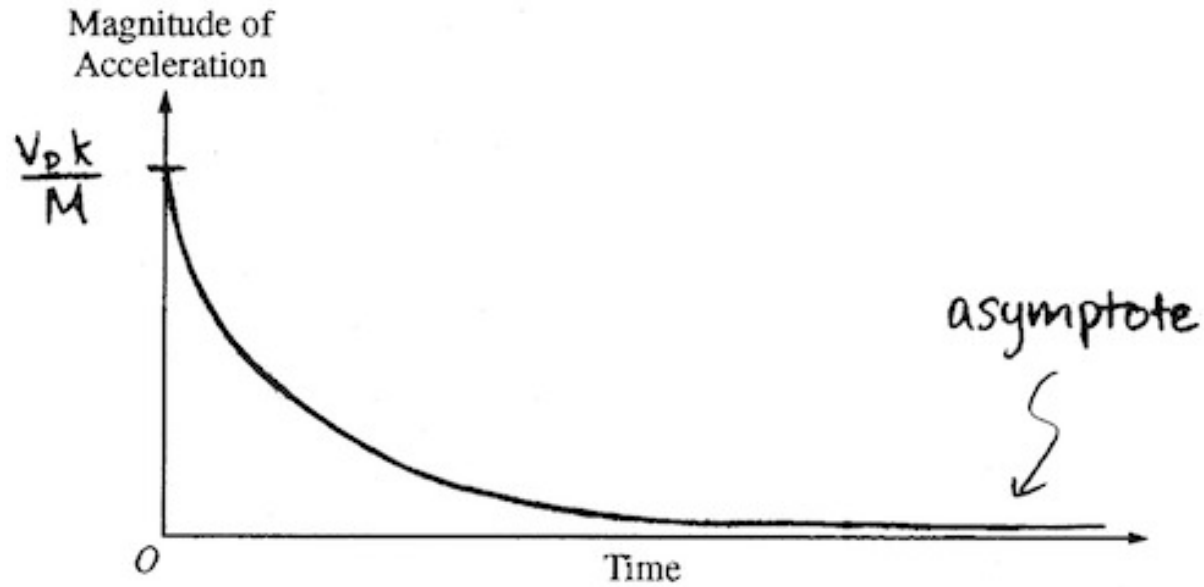
$$e^{-\frac{k}{m} t} = \frac{v}{V_0}$$

$$V_0 e^{-\frac{k}{m} t} = v$$

**1 point:** For separating the variables and integrating

**1 point:** For a correct expression for the velocity as a function of time

Part e(iii) (3) points)



**1 point:** For a graph with a finite intercept on the vertical axis

**1 point:** For a graph that is concave upward and asymptotic to zero

**1 point:** For labeling the initial acceleration with the correct value