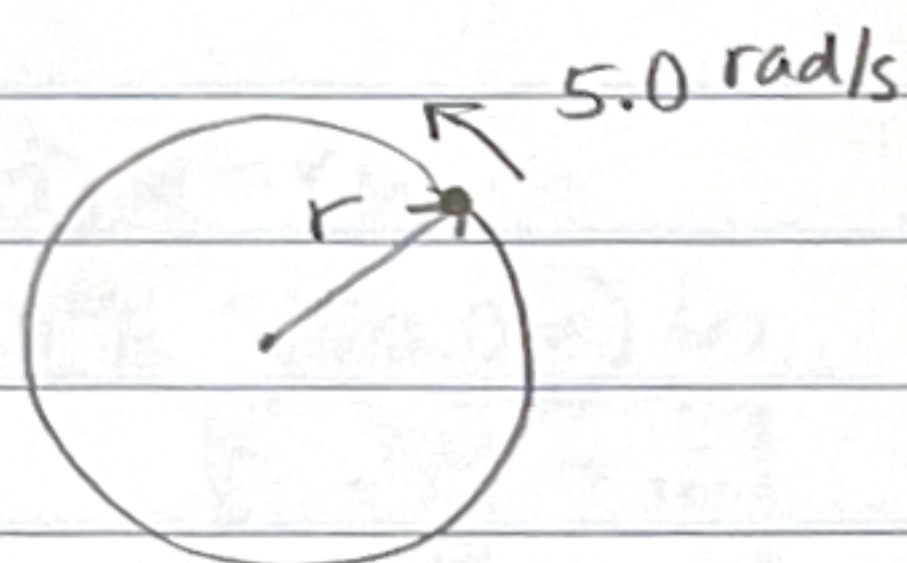


## Relating Translational and Rotational Quantities

1)  $r = 4.00 \text{ m}$   
 $\omega = 5.0 \text{ rad/s}$



a)  $a_t = r\alpha$   
 $a_t = r(0)$  since  $\omega$  is constant

$a_t = 0$

b)  $a_r = \frac{v^2}{r}$   
 $a_r = r\omega^2$

$a_r = (4.00 \text{ m})(5.0 \text{ rad/s})^2$

$a_r = 100 \text{ m/s}^2$ , toward center

b)  $a_t = 0$  because  $\omega$  is constant

$a_r = r\omega^2$

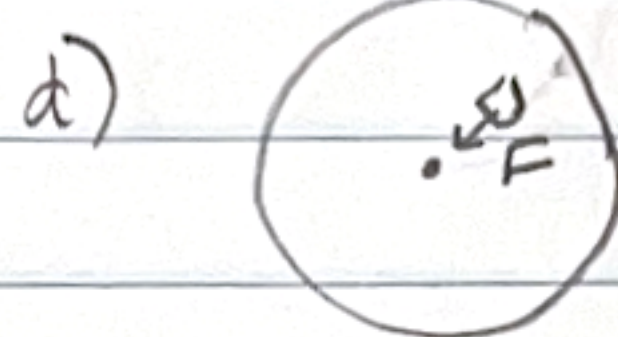
$a_r = (1.0 \text{ m})(5.0 \text{ rad/s})^2$

$a_r = 5 \text{ m/s}^2$ , toward center

c)  $v_t = r\omega$

$v_t = (1.00 \text{ m})(5.0 \text{ rad/s})$

$v_t = 5.0 \text{ m/s}$



$\Sigma F_r = m a_r$

$f_s = (1 \text{ kg}) \frac{v^2}{r}$

$f_s = (1 \text{ kg}) \frac{(5.0 \text{ m/s})^2}{1 \text{ m}}$

$f_s = 25 \text{ kg} \cdot \frac{\text{m}}{\text{s}^2}$

$f_s = 25 \text{ N}$ , toward center

2)  $d = 1.20 \text{ m}$ , so  $r = 0.60 \text{ m}$   
 $\omega = 200.0 \frac{\text{rev}}{\text{min}}$

a)  $\omega = 200.0 \frac{\text{rev}}{\text{min}} \left( \frac{2\pi \text{ rad}}{1 \text{ rev}} \right) \left( \frac{1 \text{ min}}{60 \text{ s}} \right) = 20.9 \frac{\text{rad}}{\text{s}}$

b)  $v_t = r\omega$

$v_t = (0.60 \text{ m})(20.9 \text{ rad/s})$

$v_t = 12.5 \text{ m/s}$

c)  $\omega_f = 1000.0 \text{ rev/min}$

$\Delta t = 60 \text{ s} = 1 \text{ min.}$

$\alpha = ?$

$\alpha = \frac{\Delta \omega}{\Delta t}$

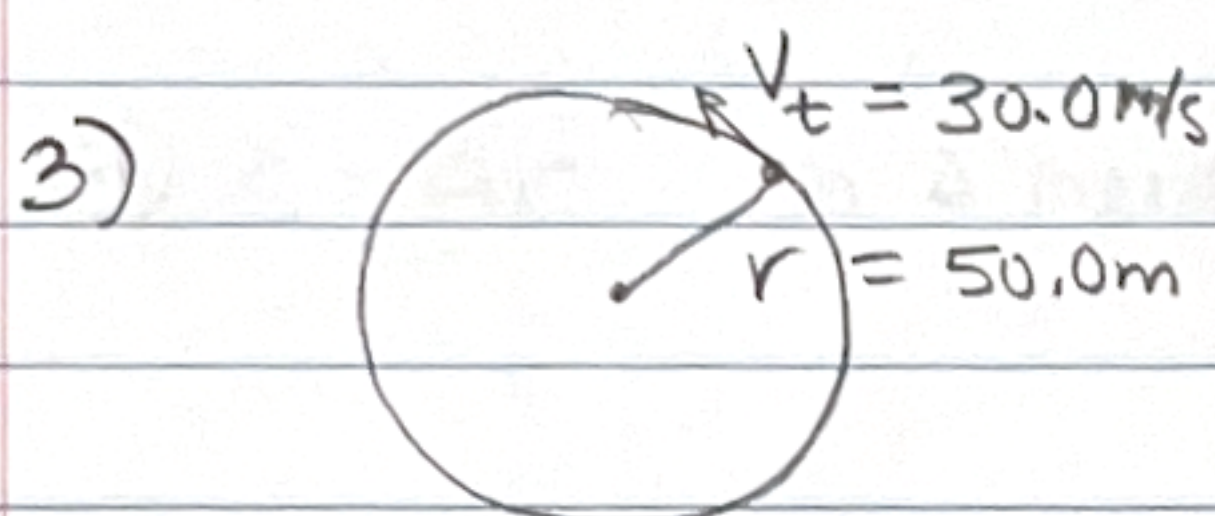
$\alpha = \frac{1000.0 \text{ rev/min} - 200.0 \text{ rev/min}}{1 \text{ min}}$

$\alpha = 800 \text{ rev/min}^2$

d)  $\Delta \theta = \omega_i \Delta t + \frac{1}{2} \alpha \Delta t^2$

$\Delta \theta = (200 \frac{\text{rev}}{\text{min}})(1 \text{ min}) + \frac{1}{2} (800 \frac{\text{rev}}{\text{min}^2})(1 \text{ min})^2$

$\Delta \theta = 600 \text{ rev}$



a)  $v = r\omega$   
 $30.0 \text{ m/s} = (50.0 \text{ m}) \omega$   
 $\boxed{0.6 \frac{\text{rad}}{\text{s}} = \omega}$

b)  $a_r = r\omega^2$   
 $a_r = (50.0 \text{ m})(0.6 \frac{\text{rad}}{\text{s}})^2$   
 $\boxed{a_r = 18 \text{ m/s}^2, \text{ toward center}}$

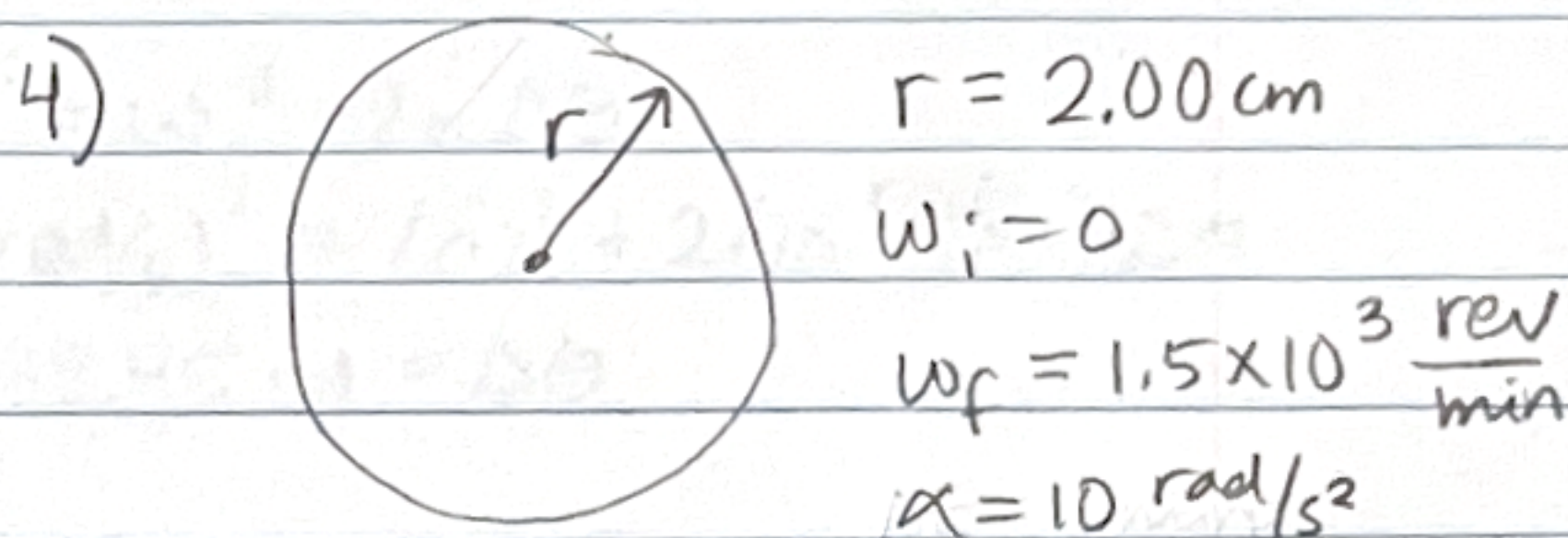
c)  $\boxed{a_t = 0}$  because  $\omega$  is constant

d)  $s = 15.0 \text{ m}$   
 $s = v \cdot \Delta t$   
 $15 \text{ m} = (30 \text{ m/s}) \Delta t$   
 $\boxed{0.5 \text{ s} = \Delta t}$

e)  $s = r\theta$   
 $15.0 \text{ m} = (50.0 \text{ m}) \theta$   
 $\boxed{0.3 \text{ rad} = \theta}$

OR  $\omega = \frac{\Delta\theta}{\Delta t}$   
 $(0.6 \frac{\text{rad}}{\text{s}}) = \frac{\Delta\theta}{0.5 \text{ s}}$   
 $\boxed{0.3 \text{ rad} = \Delta\theta}$

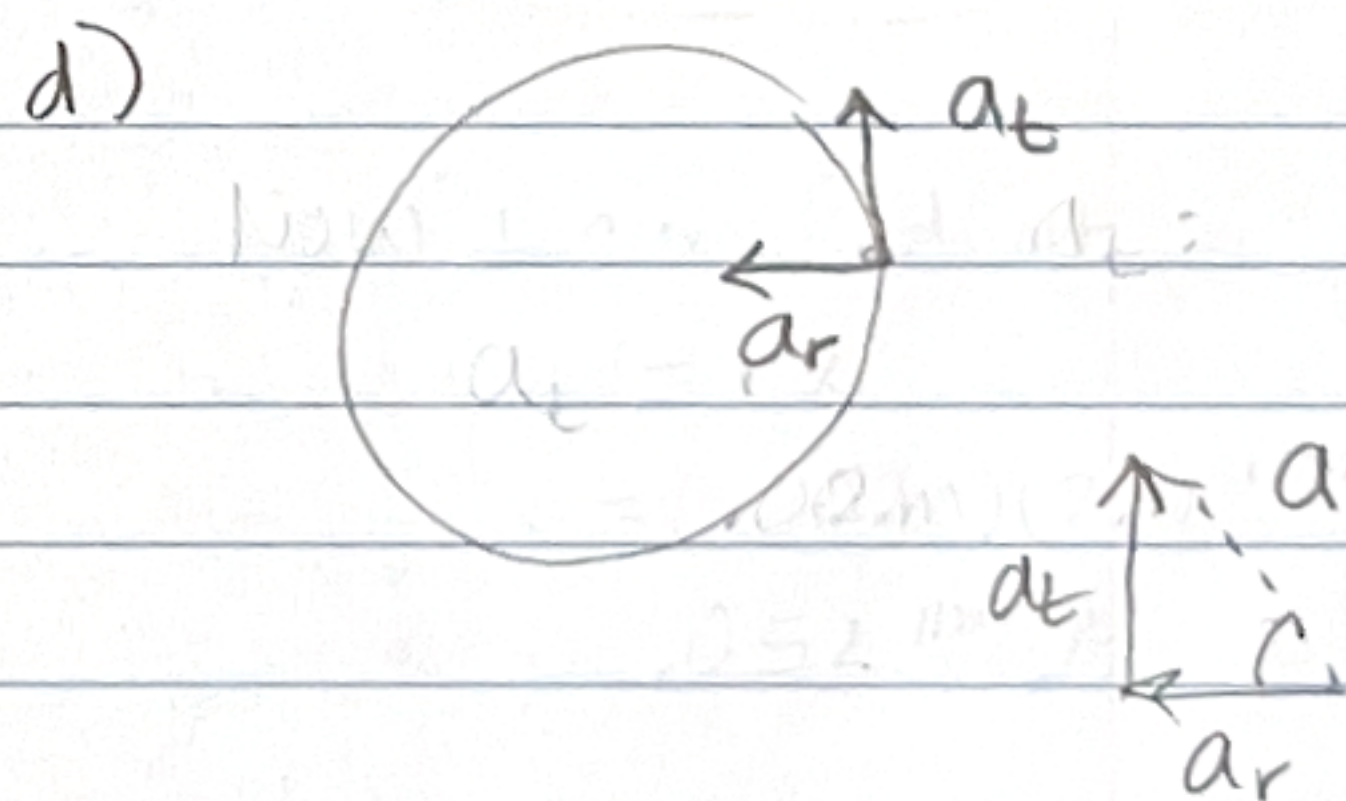
f)  $\Sigma F_r = m a_r$   
 $f_s = m a_r$   
 $\mu_s(mg) = m a_r$   
 $\mu_s = \frac{a_r}{g}$   
 $\mu_s = \frac{(18 \text{ m/s}^2)}{9.8 \text{ m/s}^2} = \boxed{1.8}$



a)  $\omega_f = 1.5 \times 10^3 \frac{\text{rev}}{\text{min}} \left( \frac{1 \text{ min}}{60 \text{ s}} \right) \left( \frac{2\pi \text{ rad}}{1 \text{ rev}} \right)$   
 $\omega_f = \boxed{157 \text{ rad/s}}$

b)  $a_t = r\alpha$   
 $a_t = (0.02 \text{ m})(10 \text{ rad/s}^2)$   
 $\boxed{a_t = 0.2 \text{ m/s}^2}$

c)  $a_r = \omega^2 r$   
 $a_r = (157 \text{ rad/s})^2 (0.02 \text{ m})$   
 $a_r = \boxed{493 \text{ m/s}^2, \text{ toward center}}$

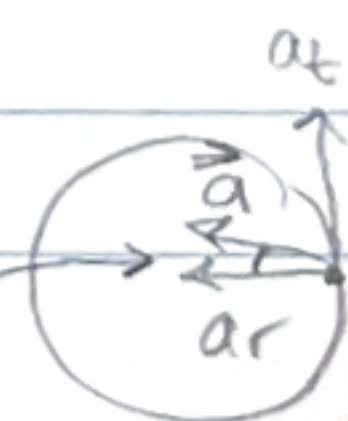


$a = \sqrt{a_r^2 + a_t^2}$   
 $a = \sqrt{(493 \text{ m/s}^2)^2 + (0.2 \text{ m/s}^2)^2}$   
 $a = 493 \text{ m/s}^2$

$\tan\theta = \frac{a_t}{a_r}$   
 $\tan\theta = \frac{0.2}{493}$

$\theta = 0.02^\circ$

$\vec{a} = 493 \text{ m/s}^2 \text{ at } 0.02^\circ$



e)  $s = \theta r$ , so I need  $\theta$ :  $\omega_f^2 = \omega_i^2 + 2\alpha \Delta\theta$   
 $(157 \text{ rad/s})^2 = (0)^2 + 2(10 \text{ rad/s}^2) \Delta\theta$   
 $1232.45 \text{ rad} = \Delta\theta$

$$s = (1232.45 \text{ rad})(.02 \text{ m})$$

$$s = 25 \text{ m}$$